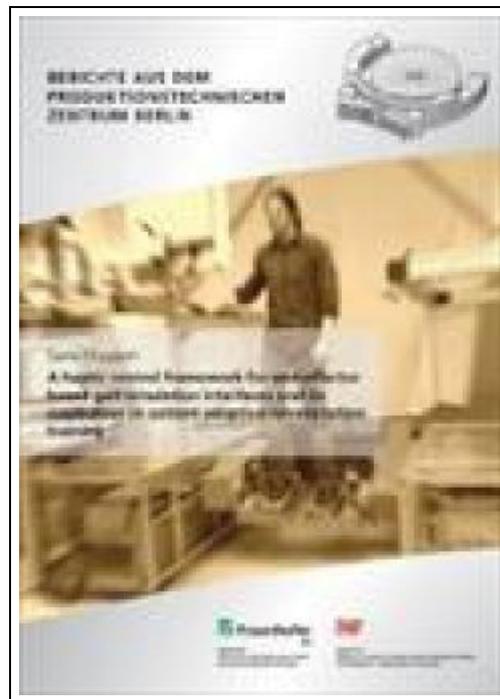


## A haptic control framework for end-effector based gait simulation interfaces and its application in patient-adaptive rehabilitation training



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